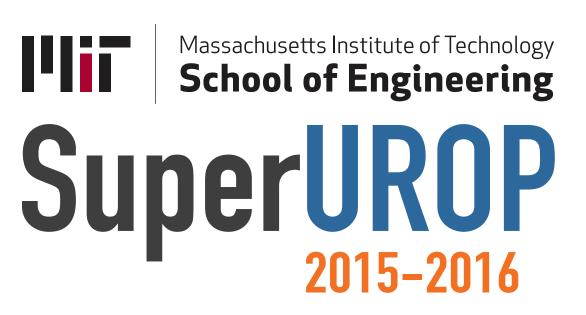
# Understanding Video with Deep Convolutional Neural Networks



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### **Computer Vision**

Useful for many tasks, including pedestrian detection for self-driving cars

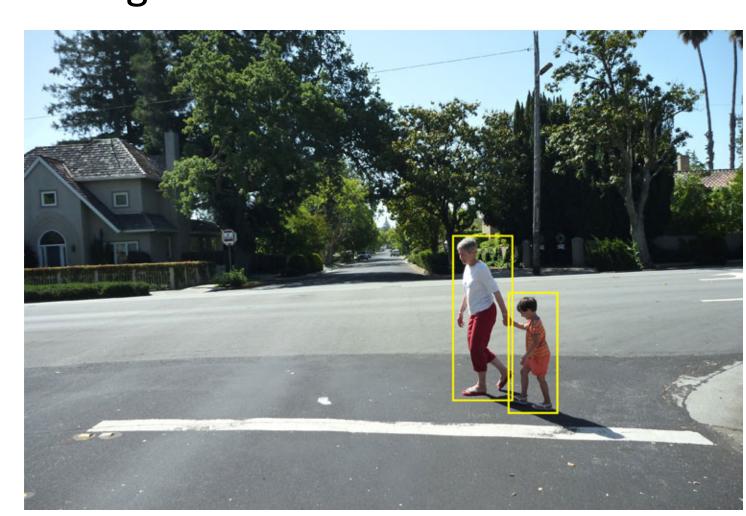
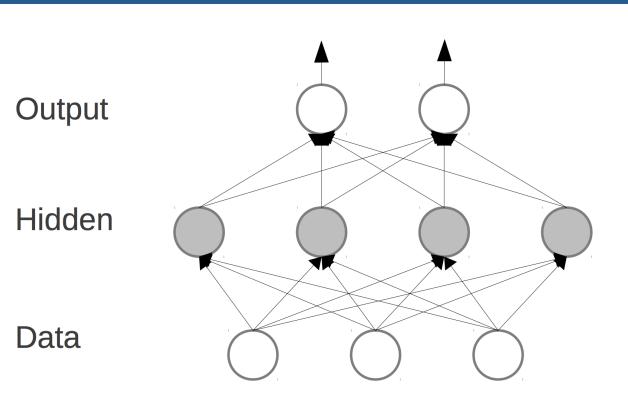


Photo from [1

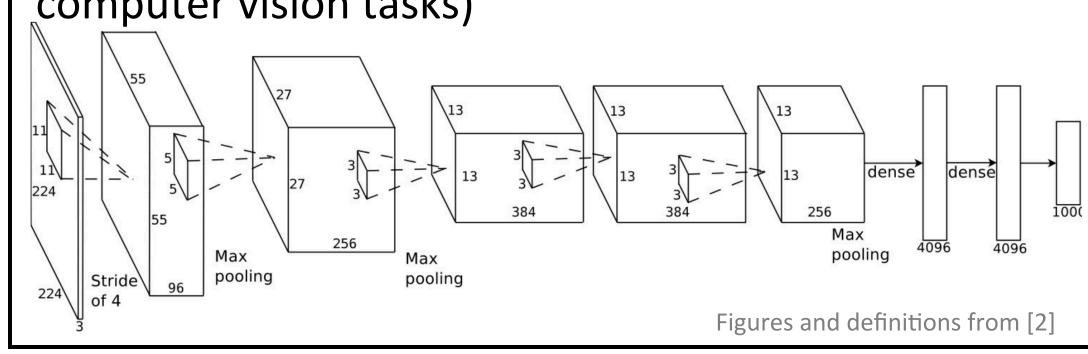
Much successful work on images, but less done on videos (labeling videos is expensive)

#### **Neural Networks**

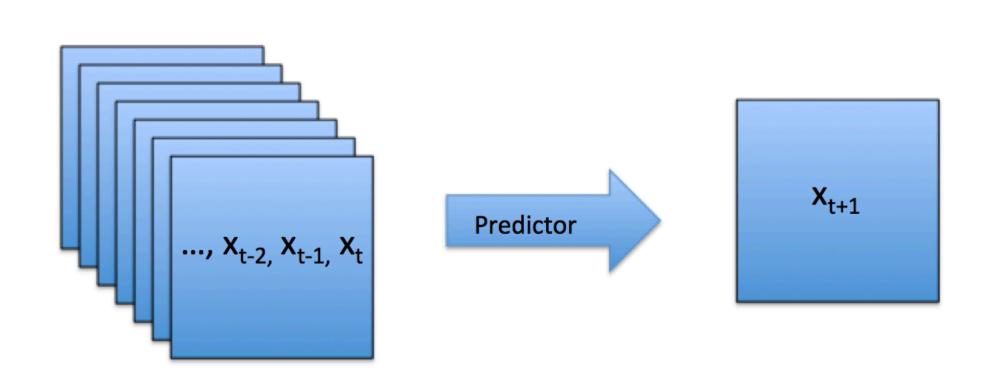
Neural network computes a differentiable function of its input



A convolutional neural network (CNN) applies the same function to each section of the input (good for computer vision tasks)



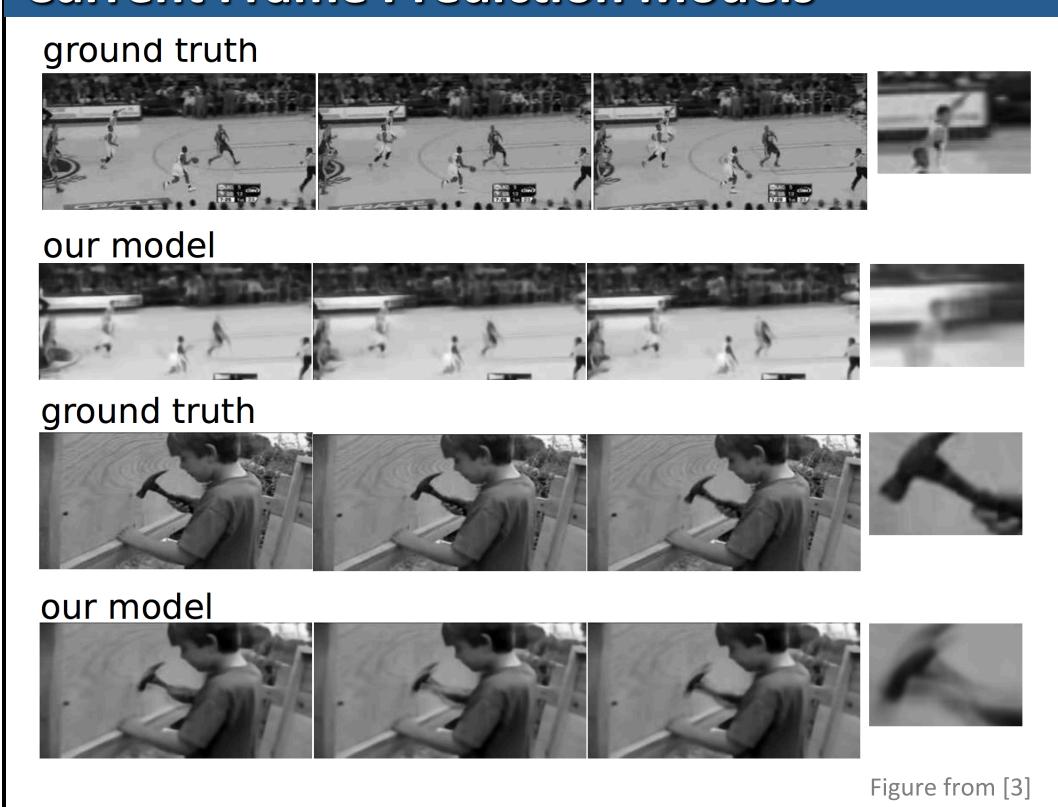
#### **Unsupervised Learning for Frame Prediction**



Given past frames, predict future frame

- The previous frames are inputs to the predictor, which attempts to generate the next frame  $x_{t+1}$
- Cost function computes how close predicted frame pixels are to actual next frame pixels

#### **Current Frame Prediction Models**



Problem: Predictor tends to output mean frame

#### **Current status**

- Implementation of simple prediction model in Caffe, a popular open-source library for CNNs [4]
- Current model generates future frame given one past frame
- Simplified problem to prediction of cropped frame based on object detector bounding boxes
  [5]
- Considering cost functions that will hopefully improve issue with outputting mean frame

## **Next Steps and References**

- Try out different network architectures (number of layers, dimensions, etc.) and determine which is the most successful for prediction
- Experiment with different cost functions: do any yield predictions that are better than just mean?
- Implement LSTM (Long Short Term Memory) network for learning greater context in videos

#### References

- [1] http://www.nvidia.com/content/tegra/automotive/images/driver-assistance/pedestrian-detection-large.jpg
- [2] http://www.image-net.org/challenges/LSVRC/2012/supervision.pdf
- [3] http://arxiv.org/abs/1412.6604
- [4] http://caffe.berkeleyvision.org/
- [5] http://arxiv.org/abs/1311.2524